

SC7: Inductive Programming and Knowledge-level Learning

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IK'13

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- 6 Analytical vs. Generate-and-Test
- 7 Example: Analytical IP (Thesys)

Knowledge Level Learning

- opposed to low-level (statistical) learning
- learning as generalization of symbol structures (rules) from experience
- “white-box” learning: learned hypotheses are verbalizable, can be inspected, communicated

Examples:

- Classification/Concepts:
IF odor=almond THEN poisonous
IF cap-shape=conical & gill-color=grey THEN poisonous
- Recursive Concepts:
ancestor(X,Y) :- parent(X,Y).
ancestor(X,Y) :- parent(X,Z), ancestor(Z,Y).
- Simple action rules:
IF distance-to-object < threshold THEN STOP
- Recursive action rules:
e.g., Tower of Hanoi (to be seen later)

Approaches to Symbolical Learning

Machine Learning Approaches

- Grammar Inference
- Decision Tree Algorithms
- Inductive Logic Programming
- Evolutionary Programming
- Inductive (functional) Programming

Inductive Programming

- Very special branch of machine learning
- Learning programs from *incomplete* specifications, typically I/O examples or constraints

Overview

- Lecture 1: Introduction to IP
 - ▶ Background
 - ▶ Basic Concepts
 - ▶ Summers' THESYS system
- Lecture 2: Approaches to IP
 - ▶ Evolutionary Programming
 - ▶ Inductive Logic Programming
- Lecture 3: Analytical Inductive Programming
 - ▶ The IGOR system
 - ▶ Applications to Cognitive Tasks

References

Websites:

<http://www.inductive-programming.org/>

<http://www.cogsys.wiai.uni-bamberg.de/aaip/>

Books/Handbook Contributions/Special Issues:

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P. Flener and D. Partridge (guest eds.), 2001, *Special Issue on Inductive Programming*, *Automated Software Engineering*, 8(2).

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Emanuel Kitzelmann (2009). Inductive Programming - A Survey of Program Synthesis Techniques. In: Ute Schmid, Emanuel Kitzelmann, Rinus Plasmeijer (eds.): *Proceedings of the ACM SIGPLAN Workshop on Approaches and Applications of Inductive Programming* (AA IP 2009, Edinburgh, Scotland, September 4). Springer LNCS 5812.

IP – Community

Bi-annual Workshops

Approaches and Applications of Inductive Programming

- AAIP 2005: associated with ICML (Bonn)
invited speakers: S. Muggleton, M. Hutter, F. Wyszczki
- AAIP 2007: associated with ECML (Warsaw)
invited speakers: R. Olsson, L. Hamel
- AAIP 2009: associated with ICFP (Edinburgh)
invited speakers: L. Augustsson, N. Mitchell, P. Koopman & R. Plasmeijer
Proceedings: Springer Lecture Notes in Computer Science 5812
- AAIP 2011: associated with PPDP 2011 and LOPSTR 2011 (Odense)
invited speaker: Ras Bodik
- AAIP 2013: Dagstuhl Seminare in December

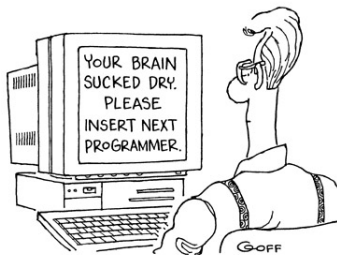
Community Page

www.inductive-programming.org

Program Synthesis

Automagic Programming

- Let the computer program itself
- Automatic code generation from (non-executable) specifications very high level programming
- Not intended for software development in the large but for semi-automated synthesis of functions, modules, program parts



Approaches to Program Synthesis

Deductive and transformational program synthesis

- Complete formal specifications (vertical program synthesis)
- e.g. KIDS (D. Smith)
- High level of formal education is needed to write specifications
- Tedious work to provide the necessary axioms (domain, types, ...)
- Very complex search spaces

$$\forall x \exists y \ p(x) \rightarrow q(x, y)$$

$$\forall x \ p(x) \rightarrow q(x, f(x))$$

Example

*last(l) \Leftarrow find z such that for some y, $l = y \circ [z]$
where *islist(l)* and $l \neq []$ (Manna & Waldinger)*

Approaches to Program Synthesis

Inductive program synthesis

- Very special branch of machine learning
- Learning programs from *incomplete* specifications, typically I/O examples or constraints
- Inductive programming (IP) for short

(Flener & Schmid, AI Review, 29(1), 2009; Encyclopedia of Machine Learning, 2010; Schmid, Kitzelmann & Plasmeijr, AAIP 2009)

IP – Contributing Areas

Inductive Inference of
Programs from Examples

Machine Learning

Modeling human programming
knowledge, skills, strategies

Artificial Intelligence



Software Engineering

Automated code generation
example-driven programming

**Functional/Declarative
Programming**

**Functional/Declarative
Programming**

Code generation from
incomplete specifications

Inductive Programming Example

Learning last

I/O Examples

```
last [a]      = a
```

```
last [a,b]    = b
```

```
last [a,b,c]  = c
```

```
last [a,b,c,d] = d
```

Generalized Program

```
last [x]      = x
```

```
last (x:xs)   = last xs
```

Some Syntax

```
-- sugared
```

```
[1,2,3,4]
```

```
-- normal infix
```

```
(1:2:3:4:[])
```

```
-- normal prefix
```

```
((:) 1
```

```
  ((:) 2
```

```
    ((:) 3
```

```
      ((:) 4
```

```
        []))))
```

Inductive Programming – Basics

IP is search in a class of programs (hypothesis space)

Program Class characterized by:

Syntactic building blocks:

- **Primitives**, usually data constructors
- **Background Knowledge**, additional, problem specific, user defined functions
- **Additional Functions**, automatically generated

Restriction Bias

syntactic restrictions of programs in a given language

Result influenced by:

Preference Bias

choice between syntactically different hypotheses

Inductive Programming – Approaches

- Typical for declarative languages (LISP, PROLOG, ML, HASKELL)
- Goal: finding a program which covers *all* input/output examples *correctly* (no PAC learning) and (recursively) generalizes over them
- Two main approaches:
 - ▶ **Analytical, data-driven:**
detect regularities in the I/O examples (or traces generated from them) and generalize over them (folding)
 - ▶ **Generate-and-test:**
generate syntactically correct (partial) programs, examples only used for testing

Inductive Programming – Approaches

Generate-and-test approaches

- ILP (90ies): FFOIL (Quinlan) (sequential covering)
- evolutionary: ADATE (Olsson)
- enumerative: MAGICHASKELLER (Katayama)
- also in functional/generic programming context: automated generation of instances for data types in the model-based test tool G \forall st (Koopmann & Plasmeijer)

Inductive Programming – Approaches

Analytical Approaches

- Classical work (70ies–80ies):
THESYS (Summers), Biermann, Kodratoff
learn linear recursive Lisp programs from traces
- ILP (90ies):
Golem, Progol (Muggleton), Dialogs (Flener)
inverse resolution, Θ -subsumption, schema-guided
- IGOR1 (Schmid, Kitzelmann; extension of THESYS)
IGOR2 (Kitzelmann, Hofmann, Schmid)

Summers' Thesis

(Summers (1977), A methodology for LISP program construction from examples, Journal ACM)

Two Step Approach

- Step 1: Generate traces from I/O examples
- Step 2: Fold traces into recursion

Generate Traces

- Restriction of input and output to nested lists
- Background Knowledge:
 - ▶ Partial order over lists
 - ▶ Primitives: `atom`, `cons`, `car`, `cdr`, `nil`
- Rewriting algorithm with unique result for each I/O pair: characterize I by its structure (lhs), represent O by expression over I (rhs)

↔ restriction of synthesis to structural problems over lists (abstraction over elements of a list) not possible to induce `member` or `sort`

Example: Rewrite to Traces

I/O Examples

$\text{nil} \rightarrow \text{nil}$

$(A) \rightarrow ((A))$

$(A B) \rightarrow ((A) (B))$

$(A B C) \rightarrow ((A) (B) (C))$

Traces

$F_L(x) \leftarrow$ (atom(x) \rightarrow nil,
atom(cdr(x)) \rightarrow cons(x, nil),
atom(cddr(x)) \rightarrow cons(cons(car(x), nil), cons(cdr(x), nil)),
T \rightarrow cons(cons(car(x), nil), cons(cons(cadr(x), nil),
cons(cddr(x), nil))))

Example: Deriving Fragments

Unique Expressions for Fragment (A B)

(x, (A B)),
(car[x], A),
(cdr[x], (B)),
(cadr[x], B),
(caddr[x], ())

Combining Expressions

$((A) (B)) = \text{cons}[(A); ((B))] = \text{cons}[\text{cons}[A, ()]; \text{cons}[(B), ()]]$.

Replacing Values by Functions

$\text{cons}[\text{cons}(\text{car}[x]; ()); \text{cons}[\text{cdr}[x]; ()]]$

Folding of Traces

- Based on a program scheme for linear recursion (restriction bias)
- Synthesis theorem as justification
- Idea: inverse of fixpoint theorem for linear recursion
- Traces are k th unfolding of an unknown program following the program scheme
- Identify differences, detect recurrence

$$\begin{aligned} F(x) &\leftarrow (p_1(x) \rightarrow f_1(x), \\ &\quad \dots, \\ &\quad p_k(x) \rightarrow f_k(x), \\ &\quad T \rightarrow C(F(b(x)), x)) \end{aligned}$$

Example: Fold Traces

kth unfolding

$$\begin{aligned} F_L(x) \leftarrow & (\text{atom}(x) \rightarrow \text{nil}, \\ & \text{atom}(\text{cdr}(x)) \rightarrow \text{cons}(x, \text{nil}), \\ & \text{atom}(\text{cddr}(x)) \rightarrow \text{cons}(\text{cons}(\text{car}(x), \text{nil}), \text{cons}(\text{cdr}(x), \text{nil})), \\ & \text{T} \rightarrow \text{cons}(\text{cons}(\text{car}(x), \text{nil}), \text{cons}(\text{cons}(\text{cadr}(x), \text{nil}), \\ & \quad \text{cons}(\text{cddr}(x), \text{nil})))) \end{aligned}$$

Differences:

$$p_2(x) = p_1(\text{cdr}(x))$$

$$p_3(x) = p_2(\text{cdr}(x))$$

$$p_4(x) = p_3(\text{cdr}(x))$$

$$f_2(x) = \text{cons}(x, f_1(x))$$

$$f_3(x) =$$

$$\text{cons}(\text{cons}(\text{car}(x), \text{nil}), f_2(\text{cdr}(x)))$$

$$f_4(x) =$$

$$\text{cons}(\text{cons}(\text{car}(x), \text{nil}), f_3(\text{cdr}(x)))$$

Recurrence Relations:

$$p_1(x) = \text{atom}(x)$$

$$p_{k+1}(x) = p_k(\text{cdr}(x)) \text{ for } k = 1, 2, 3$$

$$f_1(x) = \text{nil}$$

$$f_2(x) = \text{cons}(x, f_1(x))$$

$$f_{k+1}(x) = \text{cons}(\text{cons}(\text{car}(x), \text{nil}), f_k(\text{cdr}(x)))$$

$$\text{for } k = 2, 3$$

Example: Fold Traces

kth unfolding

$$F_L(x) \leftarrow \begin{aligned} &(\text{atom}(x) \rightarrow \text{nil}, \\ &\text{atom}(\text{cdr}(x)) \rightarrow \text{cons}(x, \text{nil}), \\ &\text{atom}(\text{cddr}(x)) \rightarrow \text{cons}(\text{cons}(\text{car}(x), \text{nil}), \text{cons}(\text{cdr}(x), \text{nil})), \\ &T \rightarrow \text{cons}(\text{cons}(\text{car}(x), \text{nil}), \text{cons}(\text{cons}(\text{cadr}(x), \text{nil}), \\ &\quad \text{cons}(\text{cddr}(x), \text{nil})))) \end{aligned}$$

Folded Program

$$\begin{aligned} \text{unpack}(x) &\leftarrow \begin{aligned} &(\text{atom}(x) \rightarrow \text{nil}, \\ &T \rightarrow u(x)) \end{aligned} \\ u(x) &\leftarrow \begin{aligned} &(\text{atom}(\text{cdr}(x)) \rightarrow \text{cons}(x, \text{nil}), \\ &T \rightarrow \text{cons}(\text{cons}(\text{car}(x), \text{nil}), u(\text{cdr}(x)))) \end{aligned} \end{aligned}$$

Summers' Synthesis Theorem

- Based on fixpoint theory of functional program language semantics. (Kleene sequence of function approximations: a partial order can be defined over the approximations, there exists a supremum, i.e. least fixpoint)
- Idea: If we assume that a given trace is the k -th unfolding of an unknown linear recursive function, then there must be regular differences which constitute the stepwise unfoldings and in consequence, the trace can be generalized (folded) into a recursive function

Illustration of Kleene Sequence

Defined for no input

$$U^0 \leftarrow \Omega$$

Defined for empty list

$$U^1 \leftarrow \begin{array}{l} (atom(x) \rightarrow nil, \\ T \rightarrow \Omega) \end{array}$$

Defined for empty list and lists with one element

$$U^2 \leftarrow \begin{array}{l} (atom(x) \rightarrow nil, \\ atom(cdr(x)) \rightarrow cons(x, nil), \\ T \rightarrow \Omega) \end{array}$$

... Defined for lists up to n elements